# KPZ limit for interacting particle systems —Introduction—

Tadahisa Funaki (舟木 直久)

Waseda University (早稲田大学)

November 17th+19th, 2020

Yau Mathematical Sciences Center, Mini-Course, Nov 17-Dec 17, 2020 Lecture No 1

# Plan of the course (10 lectures)

- 1 Introduction
- 2 Supplementary materials

Brownian motion, Space-time Gaussian white noise, (Additive) linear SPDEs, (Finite-dimensional) SDEs, Martingale problem, Invariant/reversible measures for SDEs, Martingales

- 3 Invariant measures of KPZ equation (F-Quastel, 2015)
- 4 Coupled KPZ equation by paracontrolled calculus (F-Hoshino, 2017)
- 5 Coupled KPZ equation from interacting particle systems (Bernardin-F-Sethuraman, 2020+)
  - 5.1 Independent particle systems
  - 5.2 Single species zero-range process
  - 5.3 *n*-species zero-range process
  - 5.4 Hydrodynamic limit, Linear fluctuation
  - 5.5 KPZ limit=Nonlinear fluctuation

# Plan of Lecture No 1

Introduction to the course

- 1 KPZ equation
- 2 Heuristic derivation of KPZ equation (following the original KPZ paper, 1986)
- 3 Reason for KPZ equation to attract a lot of attention
- 4 III-posedness, Renormalization
- 5 Cole-Hopf solution, Multiplicative linear stochastic heat equation, Itô's formula
- 6 KPZ equation from interacting particle systems (WASEP)
- 7 Quick overview of the course

# 1. KPZ equation

► The KPZ (Kardar-Parisi-Zhang, 1986) equation describes the motion of growing interface with random fluctuation.



- (Right Fig) h = h(t, x) ∈ ℝ denotes height of interface measured from the x-axis at time t and position x.
- Video of combustion experiment by Laser shot: srep00034-s2.mov, srep00034-s3.mov (Takeuchi-Sano)

• KPZ is an equation for height function h(t, x):

 $\partial_t h = \frac{1}{2} \partial_x^2 h + \frac{1}{2} (\partial_x h)^2 + \dot{W}(t, x), \quad x \in \mathbb{T} \text{ (or } \mathbb{R}\text{).}$ (1)

where  $\mathbb{T}\equiv\mathbb{R}/\mathbb{Z}=[0,1).$ 

- ► We consider in 1D on a whole line ℝ or on a finite interval T under periodic boundary condition.
- The coefficients <sup>1</sup>/<sub>2</sub> are not important, since we can change them under some scaling.
- W(t, x) is a space-time Gaussian white noise with mean 0 and covariance structure:

$$E[\dot{W}(t,x)\dot{W}(s,y)] = \delta(t-s)\delta(x-y).$$
(2)

- This means that the noise is independent if (t, x) is different, since "Gaussian property+0-correlation" means independence.
- However,  $\dot{W}(t,x)$  is realized only as a generalized function (distribution).

2. Heuristic derivation of KPZ equation

- We give a derivation of KPZ equation following the original KPZ paper 1986.
- Consider a motion of interface (curve) growing upward with normal velocity:

$$V = \kappa + A,$$

where  $\kappa$  is the (signed) curvature and A > 0 is a constant.



The interface dynamics can be described by an equation for its height function h(t, x) assuming that the interface in R<sup>2</sup> is represented as a graph:

$$\gamma_t = \{(x, y); y = h(t, x), x \in \mathbb{R}\} \subset \mathbb{R}^2.$$

The dynamics "V = κ + A" can be rewritten into the following nonlinear PDE for h(t, x)

$$\partial_t h = \frac{\partial_x^2 h}{1 + (\partial_x h)^2} + A(1 + (\partial_x h)^2)^{1/2}$$
 (3)



Indeed, (3) can be derived as follows.

First, note that the normal vector  $\overline{n}$  to the curve  $\gamma_h = \{(x, y); y = h(x), x \in \mathbb{R}\} \subset \mathbb{R}^2$ at the point (x, y) is given by

$$\vec{n} = rac{1}{\left(1 + (\partial_x h(x))^2\right)^{1/2}} \begin{pmatrix} -\partial_x h(x) \\ 1 \end{pmatrix}$$

$$\mathsf{pf}) \stackrel{\rightharpoonup}{n} \perp \begin{pmatrix} 1 \\ \partial_x h(x) \end{pmatrix} (= \mathsf{tangent vector to } \gamma_h) \mathsf{ and } \mid \stackrel{\frown}{n} \mid = 1.$$

The interface growth to the direction n is equivalent to the growth of the height function h to the vertical direction m, where

$$\vec{m} = \begin{pmatrix} 0\\ \left(1 + (\partial_x h(x))^2\right)^{1/2} \end{pmatrix}$$

pf) We can check  $(\vec{m} - \vec{n}) \perp \vec{n}$ 

The curvature of the curve γ<sub>h</sub> = {y = h(x)} at (x, y) is given by

$$\kappa = rac{\partial_x^2 h(x)}{\left(1 + (\partial_x h(x))^2
ight)^{3/2}}.$$

Summarizing these observations, the interface growing equation  $V = \kappa + A$  can be written as

$$\partial_t h = \left\{ \frac{\partial_x^2 h}{(1 + (\partial_x h)^2)^{3/2}} + A \right\} (1 + (\partial_x h)^2)^{1/2},$$

i.e. we obtain (3):

$$\partial_t h = rac{\partial_x^2 h}{1+(\partial_x h)^2} + A(1+(\partial_x h)^2)^{1/2},$$

for the height function h = h(t, x).

$$egin{aligned} \partial_t h &= rac{\partial_x^2 h}{1+(\partial_x h)^2} + A\left\{(1+(\partial_x h)^2)^{1/2}-1
ight\}\ &\simeq \partial_x^2 h + rac{A}{2}(\partial_x h)^2, \end{aligned}$$

i.e.

$$\partial_t h = \partial_x^2 h + \frac{A}{2} (\partial_x h)^2,$$

at least if  $|\partial_x h|$  is small, i.e., if we take the leading effect of this equation.

Note that  $u := \partial_x h$  is a solution of (viscous) Burgers equation:

$$\partial_t u = \partial_x^2 u + \frac{A}{2} \partial_x u^2.$$

Kardar-Parisi-Zhang equation (KPZ, 1986) is obtained by taking the fluctuation effect due to space-time independent noise W(t, x) into account:

 $\partial_t h = \frac{1}{2} \partial_x^2 h + \frac{1}{2} (\partial_x h)^2 + \dot{W}(t, x).$ 

Here h = h(t, x, ω) and W(t, x) = W(t, x, ω) is the space-time Gaussian white noise defined on a certain probability space (Ω, F, P) with mean 0 and covariance structure

$$E[\dot{W}(t,x)\dot{W}(s,y)] = \delta(x-y)\delta(t-s).$$

- We took A = 1 and put  $\frac{1}{2}$  in front of  $\partial_x^2 h$ .
- Only leading terms are taken in the equation.
- This simplification is essential in view of the scaling property or universality related to the KPZ equation.

Mathematically, everything is built on a probability space  $(\Omega, \mathcal{F}, P)$ , i.e.  $\Omega$  is a set,  $\mathcal{F}$  is a  $\sigma$ -field of  $\Omega$ , P is a measure on  $(\Omega, \mathcal{F})$  s.t.  $P(\Omega) = 1$ .

#### 3. Reason for KPZ equation to attract a lot of attention

▶  $\frac{1}{3}$ -power law (instead of  $\frac{1}{2}$ -law in usual CLT): Fluctuation of height function at a single point x = 0:

$$h(t,0) \asymp c_1 t + c_2 t^{\frac{1}{3}} \zeta_{TW},$$

in particular,  $Var(h(t,0)) = O(t^{\frac{2}{3}})$ , as  $t \to \infty$ , i.e. the fluctuations of h(t,0) are of order  $t^{\frac{1}{3}}$ . Subdiffusive behavior different from CLT (=diffusive behavior).

- The limit distribution of h(t, 0) under scaling is given by the so-called Tracy-Widom distribution ζ<sub>TW</sub> (different depending on initial distributions). (instead of Gaussian distribution in CLT)
- ► KPZ universality class, 1:2:3 scaling, KPZ fixed point
- Integrable Probability

- Singular ill-posed SPDEs:
  - Hairer: Regularity structures, KPZ equation, dynamic  $P(\phi)_d$ -model, Parabolic Anderson model
  - Gubinelli-Imkeller-Perkowski: Paracontrolled calculus (harmonic analytic method)
  - The solution map is continuous in " $\dot{W}^{\varepsilon}$  and their (finitely many) polynomials".
  - Renormalization is required (called subcritical case).
- Microscopic interacting particle systems
  - Bertini-Giacomin (1997) was the first to this direction.
  - This is one of main purposes of this course.

#### 4. III-posedness, Renormalization

Nonlinearity and roughness of noise conflict with each other.
W(t,x) ∈ C<sup>-d+1/2-</sup> := ∩ C<sup>-d+1/2-δ</sup> a.s. if x ∈ T<sup>d</sup> or ℝ<sup>d</sup>. (Construction will be discussed later → Lecture No 2).
C<sup>α</sup>: (Hölder-)Besov space with exponent α ∈ ℝ.
The linear SPDE (d = 1): (Schauder effect) ∂<sub>t</sub>h = 1/2∂<sup>2</sup><sub>x</sub>h + W(t,x), x ∈ T

obtained by dropping the nonlinear term has a solution  $h \in C^{\frac{1}{4}-,\frac{1}{2}-}([0,\infty) \times \mathbb{T}) := \underset{\delta > 0}{\cap} C^{\frac{1}{4}-\delta,\frac{1}{2}-\delta}([0,\infty) \times \mathbb{T})$  a.s.

(This will be discussed later  $\rightarrow$  Lecture No 2).

- Therefore, no way to define the nonlinear term (∂<sub>x</sub>h)<sup>2</sup> in
   (1) in a usual sense.
- Actually, it requires a renormalization. The following Renormalized KPZ equation with compensator δ<sub>x</sub>(x) (= +∞) would have a meaning (cf. Cole-Hopf solution):
   ∂<sub>t</sub>h = <sup>1</sup>/<sub>2</sub>∂<sup>2</sup><sub>x</sub>h + <sup>1</sup>/<sub>2</sub>{(∂<sub>x</sub>h)<sup>2</sup> δ<sub>x</sub>(x)} + W(t,x).

5. Cole-Hopf solution, Multiplicative linear stochastic heat equation, Itô's formula

Recall classical Cole-Hopf (Hopf-Cole) transformation: Let u be a solution of viscous Burgers equation:

$$\partial_t u = \frac{1}{2} \partial_x^2 u + \frac{1}{2} \partial_x u^2 + \partial_x \zeta(t, x),$$

with smooth  $\zeta$ . Then,  $Z(t, x) := e^{\int_{-\infty}^{x} u(t,y)dy}$  solves the linear heat equation

$$\partial_t Z = \frac{1}{2} \partial_x^2 Z + Z \zeta.$$

In fact,

$$\partial_t Z = Z \cdot \int_{-\infty}^{\infty} \partial_t u(t, y) dy$$
  
=  $Z \cdot (\frac{1}{2} \partial_x u + \frac{1}{2} u^2 + \zeta),$ 

while

$$\partial_x^2 Z = \partial_x (uZ) = \partial_x u \cdot Z + u \cdot \partial_x Z$$
$$= \partial_x u \cdot Z + u^2 \cdot Z.$$

This leads to the above heat equation for Z.

Motivated by this and regarding u = ∂<sub>x</sub>h, consider the (multiplicative) linear stochastic heat equation (SHE) for Z = Z(t, x, ω):

$$\partial_t Z = \frac{1}{2} \partial_x^2 Z + Z \dot{W}(t, x), \quad x \in \mathbb{R},$$
 (4)

with a multiplicative noise (defined in Itô's sense).
The solution Z(t) of (4) can be defined in a generalized functions' sense or in a mild form (Duhamel's formula):

$$Z(t,x) = \int_{\mathbb{R}} p(t,x,y)Z(0,y)dy + \int_0^t \int_{\mathbb{R}} p(t-s,x,y)Z(s,y)dW(s,y),$$

where  $p(t, x, y) = \frac{1}{\sqrt{2\pi t}} e^{-(y-x)^2/(2t)}$  is the heat kernel. (4) in Itô's sense is well-posed ( $\rightarrow$  see next page)

SHE (4) defined in Stratonovich sense:

$$\partial_t Z = \frac{1}{2} \partial_x^2 Z + Z \circ \dot{W}(t, x)$$

is ill-posed. ( $\rightarrow$  see below)

These two notions of solutions (in generalized functions or mild) are equivalent, and <sup>∃</sup>unique solution s.t. Z(t) ∈ C([0,∞), C<sub>tem</sub>) a.s., where

$$\mathcal{C}_{\text{tem}} = \{ Z \in C(\mathbb{R}, \mathbb{R}); \|Z\|_r < \infty, \forall r > 0 \}, \\ \|Z\|_r = \sup_{x \in \mathbb{R}} e^{-r|x|} |Z(x)|.$$

- ▶ (Strong comparison) If  $Z(0,x) \ge 0$  for  $\forall x \in \mathbb{R}$  and Z(0,x) > 0 for  $\exists x \in \mathbb{R}$ , then  $Z(t) \in C((0,\infty), C_+)$  a.s., where  $C_+ = C(\mathbb{R}, (0,\infty))$ .
- Therefore, we can define the Cole-Hopf transformation:

$$h(t,x) := \log Z(t,x).$$
(5)

Heuristic derivation of the KPZ eq (with renormalization factor δ<sub>x</sub>(x)) from SHE (4) under the Cole-Hopf transformation (5):
▶ (Finite-dimensional) Itô's formula:

$$df(X_t) = f'(X_t) dX_t + \frac{1}{2} f''(X_t) (dX_t)^2$$

for example, for  $X_t = B_t$ ,  $(dB_t)^2 = dt$ .

In infinite-dimensional setting,

$$dW(t,x)dW(t,y) = \delta(x-y)dt \ (= \delta_x(y)dt)$$

By Itô's formula, taking f(z) = log z under the C-H transformation (5), we have

$$dh(t,x) = f'(Z(t,x))dZ(t,x) + \frac{1}{2}f''(Z(t,x))(dZ(t,x))^2.$$

Note 
$$f'(z) = (\log z)' = z^{-1}$$
,  $f''(z) = (\log z)'' = -z^{-2}$ .

Note also from SHE (4),

$$(dZ(t,x))^2 = (Z(t,x)dW(t,x))^2 = Z^2(t,x)\delta_x(x)dt.$$

• Therefore, writing  $\partial_t h$  for  $\frac{dh(t,x)}{dt}$ , we obtain

$$\partial_t h = Z^{-1} \partial_t Z - \frac{1}{2} Z^{-2} Z^2 \delta_x(x) = Z^{-1} \left( \frac{1}{2} \partial_x^2 Z + Z \dot{W} \right) - \frac{1}{2} \delta_x(x) \quad \text{(by SHE (4))} = \frac{1}{2} Z^{-1} \partial_x^2 Z + \dot{W} - \frac{1}{2} \delta_x(x).$$

▶ However, since  $h = \log Z$ , a simple computation (as we already saw for  $u = \partial_x h$ ) shows

$$Z^{-1}\partial_x^2 Z = \partial_x^2 h + (\partial_x h)^2 \qquad (=\partial_x u + u^2).$$

This leads to the KPZ eq with renormalization factor:

$$\partial_t h = \frac{1}{2} \partial_x^2 h + \frac{1}{2} \{ (\partial_x h)^2 - \delta_x(x) \} + \dot{W}(t, x).$$
 (6)

- The function h(t,x) defined by (5) is meaningful and called the Cole-Hopf solution of the KPZ equation, although the equation (1) does not make sense.
- Problem: To introduce approximations for (6), in particular, well adapted to finding invariant measures. (→ F-Quastel, Lecture No 3)
- ▶ Hairer gave a meaning to (6) without bypassing SHE.

Itô's formula for Stratonovich integral has no Itô correction term (i.e. the term with <sup>1</sup>/<sub>2</sub>). If SHE defined in Stratonovich sense were well-posed, we would obtain well-posed KPZ equation. But, this is not true.

# 6. KPZ equation from interacting particle systems

- One of our interests is to derive KPZ(-Burgers) equation from microscopic particle systems.
- Bertini-Giacomin (1997): Derivation of Cole-Hopf solution of KPZ equation from WASEP (weakly asymmetric simple exclusion process)
- For WASEP, Cole-Hopf transformation works even at microscopic level (Gärtner).

### 6.1 WASEP (weakly asymmetric simple exclusion process)

- ▶ WASEP (on ℤ) is a collection of infinite particles on ℤ.
- Each particle performs simple random walk with jump rates <sup>1</sup>/<sub>2</sub> to the right and <sup>1</sup>/<sub>2</sub> + δ to the left, under the exclusion rule that at most one particle can occupy each site, where δ > 0 is a small parameter (weak asymmetry).

• Configuration space: 
$$\mathcal{X} = \{+1, -1\}^{\mathbb{Z}}$$

• 
$$\sigma = \{\sigma(x)\}_{x \in \mathbb{Z}} \in \mathcal{X} \text{ and }$$

$$\sigma(x) = egin{array}{c} +1 \ -1 \end{pmatrix} \Longleftrightarrow egin{cases} \exists ext{ particle at } x \ \mathsf{no ext{ particle at } x} \end{bmatrix}$$



 σ<sup>x,y</sup> ∈ X denotes a new configuration after exchanging variables at x and y (i.e., if there is a particle at x and no particle at y, σ<sup>x,y</sup> is the configuration after the particle at x jumps to y. Or a particle at y jumps to x if x is vacant.)

$$\sigma^{x,y}(z) = \left\{ egin{array}{ll} \sigma(y), & ext{if } z = x, \ \sigma(x), & ext{if } z = y, \ \sigma(z), & ext{otherwise.} \end{array} 
ight.$$

• (Infinitesimal) rate of transition  $\sigma \mapsto \sigma^{z,z+1}$ , when the whole configuration is  $\sigma$ , is given by

$$c_{z,z+1}(\sigma) = \frac{1}{2} \mathbb{1}_{\{\sigma(z)=1,\sigma(z+1)=-1\}} + (\frac{1}{2} + \delta) \mathbb{1}_{\{\sigma(z)=-1,\sigma(z+1)=1\}}.$$



• Generator: For a function f on  $\mathcal{X}$ ,

$$Lf(\sigma) = \sum_{z \in \mathbb{Z}} c_{z,z+1}(\sigma) \{ f(\sigma^{z,z+1}) - f(\sigma) \}.$$

• The rate  $c_{z,z+1}$  can be decomposed as follows.

When a jump occurs,

н

$$p_+ = rac{rac{1}{2}}{1+\delta}$$
 : probability of jump to the right  $p_- = rac{rac{1}{2}+\delta}{1+\delta}$  : probability of jump to the left

Note that  $p_+ + p_- = 1$  (i.e.,  $p_{\pm}$  is a probability), by normalizing  $c_{z,z+1}$  by  $\lambda$ .

# 6.2 Construction of interacting particle systems (in general)

- Particle system is a continuous-time (jump) Markov process σ<sub>t</sub> ≡ σ<sub>t</sub>(ω) on a configuration space X of particles.
- Once infinitesimal rate c(σ) governing the random motion of particles is given, one can construct σ<sub>t</sub> as follows.
- [Distributional construction]
  - $c(\sigma)$  determines the generator of Markov process L
  - We can construct corresponding semigroup  $e^{tL}$  on  $C(\mathcal{X})$ .
  - By Markov property, e<sup>tL</sup> determines finite-dimensional distributions (joint distributions of Markov process at finitely many times).
  - ▶ By Kolmogorov's extension theorem+regularization of paths, this determines the distribution of the Markov process on the path space D([0,∞), X), which denotes the Skorohod space allowing jumps of functions.

Liggett, Interacting Particle Systems, Springer, 1985.

# [Pathwise construction]

Each particle has its own "bell". Bells are independent and ring according to the exponential holding time:

$$P(T > t) = e^{-\lambda t}, \quad t \ge 0, \ \lambda > 0.$$

Since  $E[T] = \frac{1}{\lambda}$ , "large  $\lambda$ " means that the bell rings quickly. We write  $T \stackrel{d}{=} \exp(\lambda)$ .

- λ for each particle is determined from infinitesimal rate c(σ). (For WASEP, λ = 1 + δ)
- When first bell rings, the corresponding particle makes a jump to a place chosen by certain probability {p}. (For WASEP, {p<sub>±</sub>})
- After this jump, whole system refreshes with all bells, and repeats the procedure.
- We usually consider infinite particle system, and this requires careful construction of the system.

### 6.3 Hydrodynamic limit (LLN)

- ► WASEP  $\sigma_t = (\sigma_t(x))_{x \in \mathbb{Z}}$  is constructed by the above recipe from  $c_{z,z+1}(\sigma)$  with weak asymmetry  $\delta$ .
- We first study the hydrodynamic limit (HDL) for the WASEP σ<sub>t</sub> taking δ = ε, where ε is the ratio of microscopic/macroscopic spatial sizes.
- ▶ As we will see, scalings in  $\delta$  are different for HDL/KPZ.
- Consider the macroscopic empirical measure of σ<sub>t</sub> defined by small-mass and space-time-diffusive scaling:

$$X_t(du) = arepsilon \sum_{x \in \mathbb{Z}} \sigma_{arepsilon^{-2}t}(x) \delta_{arepsilon x}(du), \quad u \in \mathbb{R},$$

or equivalently, for a test function  $\varphi \in C_0^\infty(\mathbb{R})$ ,

$$\langle X_t, \varphi \rangle = \varepsilon \sum_{x \in \mathbb{Z}} \sigma_{\varepsilon^{-2}t}(x) \varphi(\varepsilon x).$$

Theorem 1

$$X_t(du) \xrightarrow[\varepsilon \downarrow 0]{} \alpha(t, u) du$$
 (in prob),

where  $\alpha(t, u)$  is a solution of viscous Burgers equation:

$$\partial_t \alpha = \frac{1}{2} \partial_u^2 \alpha + \frac{1}{2} \partial_u (1 - \alpha^2).$$

If  $\alpha = \partial_u m$ , the equation for m is

$$\partial_t m = \frac{1}{2} \partial_u^2 m + \frac{1}{2} (1 - (\partial_u m)^2).$$

(KPZ type but without noise)

F-Sasada, CMP **299**, 2010

F, Lectures on Random Interfaces, SpringerBriefs, 2016, Theorem 2.7 for relation to Vershik curve (introducing boundary).

#### Heuristic derivation of the limit equation

► To show this theorem, we use Dynkin's formula (→ Lecture No 2):

$$\langle X_t, \varphi \rangle = \langle X_0, \varphi \rangle + \int_0^t \varepsilon^{-2} \cdot \varepsilon \sum_x (L\sigma)_{\varepsilon^{-2}s}(x) \varphi(\varepsilon x) ds + M_t^{\varepsilon}(\varphi).$$

- $\varepsilon^{-2}$  comes from the time change.
- The contribution of the martingale term M<sup>ε</sup><sub>t</sub>(φ) vanishes in the limit as ε ↓ 0. (In Lecture No 2, we will explain martingale.)

#### For the term with integral, we can compute as

$$\begin{split} \varepsilon^{-1} \sum_{x} L\sigma(x)\varphi(\varepsilon x) \\ &= \frac{\varepsilon^{-1}}{2} \sum_{x} \sigma(x) \Big[ \Big\{ \varphi(\varepsilon(x+1)) - \varphi(\varepsilon x) \Big\} - \Big\{ \varphi(\varepsilon x) - \varphi(\varepsilon(x-1)) \Big\} \Big] \\ &- \varepsilon^{-1} \cdot 2\varepsilon \sum_{x} \mathbf{1}_{\sigma(x+1)=1,\sigma(x)=-1} \Big\{ \varphi(\varepsilon(x+1)) - \varphi(\varepsilon x) \Big\} \\ &= \frac{\varepsilon^{-1}}{2} \sum_{x} \sigma(x) \varepsilon^{2} \big( \varphi''(\varepsilon x) + O(\varepsilon) \big) \\ &- \varepsilon^{-1} \cdot 2\varepsilon \sum_{x} \mathbf{1}_{\sigma(x+1)=1,\sigma(x)=-1} \varepsilon \big( \varphi'(\varepsilon x) + O(\varepsilon) \big). \end{split}$$

- Red ε was originally δ. Other ε's are from the definition of X<sub>t</sub>.
- Note that the RHS is now O(1) in ε, though it still contains nonlinear microscopic function.
- This is called the gradient property of the model.

From the above computation, the drift term is rewritten as

$$\frac{1}{2}\langle X_t,\varphi''\rangle-\varepsilon\sum_{x}A_x(\sigma_{\varepsilon^{-2}t})\varphi'(\varepsilon x)+O(\varepsilon),$$

where  $A_x(\sigma) = 21_{\sigma(x+1)=1,\sigma(x)=-1}$ .

- By the assumption of the local equilibrium, we can expect σ<sub>ε<sup>-2</sup>t</sub>(·) <sup>law</sup> ν<sub>α(t,u)</sub> asymptotically as ε ↓ 0, where ν<sub>α</sub> is the Bernoulli measure on {±1}<sup>ℤ</sup> with mean α ∈ [-1, 1].
- In particular,  $\nu_{\alpha}(\sigma(0) = 1) = \frac{\alpha+1}{2}$ ,  $\nu_{\alpha}(\sigma(0) = -1) = \frac{1-\alpha}{2}$ .
- Bernoulli product measures are invariant (and reversible) measures of the leading SEP of WASEP (or its symmetrization).
- Thus, by assuming local ergodicity, one can replace A<sub>x</sub>(σ) by its local average with proper α:

$$E^{\nu_{\alpha}}[A_{x}] = 2 \cdot \frac{\alpha+1}{2} \cdot \frac{1-\alpha}{2} = \frac{1}{2}(1-\alpha^{2}).$$

• We obtain the HD equation (closed equation) for  $\alpha(t, u)$ 

$$\partial_t \alpha = \frac{1}{2} \alpha'' + \frac{1}{2} (1 - \alpha^2)'.$$

# 6.4 Equilibrium linear fluctuation (CLT)

• We consider the fluctuation of WASEP with asymmetry  $\delta = \varepsilon$  (same as HDL) under the global equilibrium  $\nu_{\alpha}$  around its mean  $\alpha$ :

$$Y_t^{\varepsilon}(du) = \sqrt{\varepsilon} \sum_{x \in \mathbb{Z}} \left( \sigma_{\varepsilon^{-2}t}(x) - \alpha \right) \delta_{\varepsilon x}(du),$$

 Non-equilibrium fluctuation: F-Sasada-Sauer-Xie, SPA 123, 2013.

Theorem 2  

$$Y_t^{\varepsilon} \to Y_t$$
 and  $Y_t$  is a solution of linear SPDE:  
 $\partial_t Y = \frac{1}{2} \partial_u^2 Y - \alpha \partial_u Y + \sqrt{1 - \alpha^2} \partial_u \dot{W}(t, u)$ 

Heuristically, this SPDE follows by observing

$$\begin{split} \sigma - \alpha &= \sqrt{\varepsilon}Y \quad (\text{since } \sqrt{\varepsilon} = \frac{\varepsilon}{\sqrt{\varepsilon}} \text{ in } Y_t^{\varepsilon}) \\ E^{\nu_{\alpha+\sqrt{\varepsilon}Y}}[A] - E^{\nu_{\alpha}}[A] &= \frac{1}{2}(1 - (\alpha + \sqrt{\varepsilon}Y)^2) - \frac{1}{2}(1 - \alpha^2) \\ &\sim -\sqrt{\varepsilon}\alpha Y \quad (\rightarrow \text{fluctuation of drift term}) \end{split}$$

Noise term is the same as KPZ as we will discuss.

# 6.5 KPZ limit (Nonlinear fluctuation)

• We consider the fluctuation of WASEP with asymmetry  $\delta = \sqrt{\varepsilon}$  under the global equilibrium  $\nu_{\alpha}$ :

$$Y_t^{\varepsilon}(du) = \sqrt{\varepsilon} \sum_{x \in \mathbb{Z}} \left( \sigma_{\varepsilon^{-2}t}(x) - \alpha \right) \delta_{\varepsilon x - c\varepsilon^{-1/2}t}(du),$$

 ▶ Fluctuation is observed under moving frame with macroscopic speed ce<sup>-1/2</sup> (to cancel diverg. linear term).
 ▶ Channel

• Choose 
$$c = \alpha$$
.

# Theorem 3

$$Y_t^{\varepsilon} \rightarrow Y_t$$
 and  $Y_t$  is a solution of KPZ-Burgers equation:

$$\partial_t \mathbf{Y} = \frac{1}{2} \partial_u^2 \mathbf{Y} - \frac{1}{2} \partial_u \mathbf{Y}^2 + \sqrt{1 - \alpha^2} \partial_u \dot{W}(t, u).$$

If  $h_t$  is determined as  $Y_t = \partial_u h_t$ , then  $h_t$  satisfies the KPZ equation (more precisely, its Cole-Hopf solution)

$$\partial_t h = \frac{1}{2} \partial_u^2 h - \frac{1}{2} (\partial_u h)^2 + \sqrt{1 - \alpha^2} \dot{W}(t, u).$$

By the similar computation to above, we have

$$\begin{split} \langle Y_t, \varphi \rangle = \langle Y_0, \varphi \rangle + \int_0^t \varepsilon^{-2} \cdot \sqrt{\varepsilon} \sum_x (L_{\sqrt{\varepsilon}} \sigma)_{\varepsilon^{-2} s}(x) \varphi(\varepsilon x - c \varepsilon^{-1/2} s) ds \\ - \int_0^t c \sum_x (\sigma_{\varepsilon^{-2} s}(x) - \alpha) \varphi'(\varepsilon x - c \varepsilon^{-1/2} s) ds + M_t^{\varepsilon}(\varphi), \end{split}$$

where  $M_t^{\varepsilon}(\varphi)$  is a martingale different from that in HDL (but asymptotically the same as that appears in linear fluctuation).

For the martingale  $M_t^{\varepsilon}$ , under the equilibrium  $\nu_{\alpha}$ ,

$$\mathbb{E}[M_t^{\varepsilon}(\varphi)^2] \sim \varepsilon t(1-\alpha^2) \sum_{x} \varphi'(\varepsilon x)^2 \sim t(1-\alpha^2) \|\varphi'\|_{L^2(\mathbb{R})}^2.$$

 $(\rightarrow$  see Lecture No 2 for quadratic variation of M)

- This means  $M_t^{\varepsilon} \to \sqrt{1-\alpha^2}\partial_u W(t,u)$ .
- W(t, u) is an integral of  $\dot{W}(t, u)$  in t.

The first term in the drift is

$$\begin{split} \varepsilon^{-2} \cdot \sqrt{\varepsilon} \sum_{x} L_{\sqrt{\varepsilon}} \sigma(x) \varphi(\varepsilon x - c\varepsilon^{-1/2}t) \\ = \varepsilon^{-2} \cdot \frac{\sqrt{\varepsilon}}{2} \sum_{x} \sigma(x) \varepsilon^{2} \Big( \varphi''(\varepsilon x - c\varepsilon^{-1/2}t) + O(\varepsilon) \Big) \\ - \varepsilon^{-2} \cdot \sqrt{\varepsilon} \cdot \sqrt{\varepsilon} \sum_{x} A_{x}(\sigma) \varepsilon \Big( \varphi'(\varepsilon x - c\varepsilon^{-1/2}t) + O(\varepsilon) \Big). \end{split}$$

- Red √ε = δ originally. Other √ε comes from that in the definition of Y<sup>ε</sup><sub>t</sub>.
- The first term is  $\frac{1}{2}\langle Y_t, \varphi'' \rangle$  by noting that  $\sum_x \alpha \Delta \varphi = 0$ .

• The second term (after all  $\varepsilon$  cancel) is still diverging. But, we can expect by the local ergodicity (Boltzmann-Gibbs principle= combination of local averaging due to local ergodicity and Taylor expansion)

$$\begin{split} A_{x}(\sigma) &\sim E^{\nu_{\alpha+\sqrt{\varepsilon}Y_{t}(\varepsilon x-c\varepsilon^{-1/2}t)}} \Big[ A_{x}(\sigma) \Big] \\ &= \frac{1}{2} \Big( 1 - (\alpha + \sqrt{\varepsilon}Y_{t}(\varepsilon x - c\varepsilon^{-1/2}t))^{2} \Big) \\ &= \frac{1}{2} (1 - \alpha^{2}) - \alpha\sqrt{\varepsilon}Y_{t}(\varepsilon x - c\varepsilon^{-1/2}t) - \frac{1}{2}\varepsilon \frac{Y_{t}^{2}}{t}(\varepsilon x - c\varepsilon^{-1/2}t). \end{split}$$

Thus, one can expect that this term behaves as

$$\varepsilon^{-\frac{1}{2}} \alpha Y_t(\varphi') + \frac{1}{2} \langle Y_t^2, \varphi' \rangle$$

since  $\sum_{x} \frac{1}{2}(1-\alpha^2)\varphi' = 0$ .

The first term cancels with the second term in the drift  $\simeq -\varepsilon^{-\frac{1}{2}} c Y_t(\varphi')$  (originally from moving frame) if we choose the frame speed  $c = \alpha$ , and one would obtain  $\frac{1}{2}\langle Y_t^2, \varphi' \rangle$  in the limit.

 Therefore, in the limit we would have the KPZ-Burgers equation

$$\partial_t Y = \frac{1}{2} \partial_u^2 Y - \frac{1}{2} \partial_u Y^2 + \sqrt{1 - \alpha^2} \partial_u \dot{W}(t, u).$$

- Note: For Y, renormalization is unnecessary, since one would have ∂<sub>u</sub>{δ<sub>u</sub>(u)} = ∂<sub>u</sub>{const} = 0.
- The above derivation is heuristic.
- Bertini-Giacomin relied on microscopic Cole-Hopf transformation for the proof.
- Roughly, consider the process

$$\zeta_t^{\varepsilon}(x) := \exp\left\{-\gamma_{\varepsilon}\sum_{y=x_0(t)}^{x}\sigma_t(y) - \lambda_{\varepsilon}t\right\}$$

and show that  $\zeta_t^{\varepsilon}$  converges to the solution  $Z_t$  of SHE in a proper scaling.  $x_0(t)$  is a properly chosen point defined by the position of a tagged particle. See F, Lectures on Random Interfaces, p.56 for this transformation.

•  $\sum_{x_0(t)}^{x} \sigma(y)$  corresponds to the height process.

### 6.6 Other models

### Derivation of scalar KPZ (-Burgers) equation

- Bertini-Giacomin (as discussed above): Derivation from WASEP (weakly asymmetric simple exclusion process), Cole-Hopf transformation (even at microscopic level).
- Goncalves-Jara, Goncalves-Jara-Sethuraman: Derivation from general WAEP with speed change of gradient type and with Bernoulli invariant measures, or from WA zero-range process (of gradient type).
- Method: 2nd order Boltzmann-Gibbs principle, martingale formulation (called energy solutions).
- Gubinelli-Perkowski: Uniqueness of stationary energy solutions (satisfying Yaglom reversibility, i.e., - (nonlinear drift term) for time reversed process).

Derivation of coupled KPZ (-Burgers) equation

We will discuss later.

7. Quick overview of the course

- 1 Introduction
- 2 Supplementary materials

Brownian motion, Space-time Gaussian white noise, (Additive) linear SPDEs, (Finite-dimensional) SDEs, Martingale problem, Invariant/reversible measures for SDEs, Martingales

- 3 Invariant measures of KPZ equation (F-Quastel)
- 4 Coupled KPZ equation by paracontrolled calculus (F-Hoshino)
- 5 Coupled KPZ equation from interacting particle systems (Bernardin-F-Sethuraman)
  - 5.1 Independent particle systems
  - 5.2 Single species zero-range process
  - 5.3 *n*-species zero-range process
  - 5.4 Hydrodynamic limit, Linear fluctuation
  - 5.5 KPZ limit=Nonlinear fluctuation